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**Research Interests:** Computer Vision, Machine Learning, (Space) Robotics

## Education

***Postdoctoral Researcher*** 2020-2023  
GRASP Lab. Advised by Dr. Kostas Daniilidis  
CIS Department, University of Pennsylvania

***PhD in Computer Science*** 2013-2020  
George Mason University  
*Thesis:* 3D Model-Assisted Learning for Object Detection and Pose Estimation [pdf]  
*Advisor:* Prof. Jana Kosecka

***MSc in Computer Science*** 2013-2015  
George Mason University

***Diploma in Electronic and Computer Engineering*** 2006-2012  
Technical University of Crete  
*Thesis:* Field Landmark Recognition and Localization for the RobotStadium  
Online Soccer Competition [pdf]  
*Advisor:* Associate Prof. Michail G. Lagoudakis

## Positions

***Robotics Technologist*** Jan 2023-  
NASA-Jet Propulsion Laboratory  
California Institute of Technology

***Part-time Lecturer*** Spring 2022  
ESE Department, University of Pennsylvania

***Graduate Research Assistant*** Aug 2013-Dec 2019  
Computer Vision and Robotics Lab  
CS Department, George Mason University

***Research Intern*** Summer 2019  
United Imaging Intelligence, Cambridge MA

***Ph.D Research Intern - Vision and Deep Learning*** Summer 2017, 2018  
Siemens Corporate Technology, Princeton NJ

## Awards

- Co-I, “*Jupiter’s Radiant Energy Budget: Full-Disk Temporal Variations and Polar Region Analysis*”  
NASA Research Opportunities in Space and Earth Science (ROSES), 2025, \$693K  
PI: University of Houston
- Team Award, “*For successful completion of Lunar Navigation Maps (LuNaMaps) project to address key gaps in mapping for Lunar TRN*”  
Robotic Systems Section, Jet Propulsion Lab, September 2025
- Team Award, “*For technical contributions and leadership in advancing robotic autonomy*”  
Robotic Systems Section, Jet Propulsion Lab, September 2025

- Technology Spotlight Award, “*Map-based Localization for Ingenuity flights*”  
Autonomous Systems Division, Jet Propulsion Lab, August 2025
- Technology Spotlight Award, “*Photometric Calibration of JunoCam with a Data-driven Method*”  
Autonomous Systems Division, Jet Propulsion Lab, May 2024
- PI, “*Disentangling Jupiter’s Complex Atmospheric Processes Through the Application of Machine Learning Methods to JunoCam Data*”  
NASA Research Opportunities in Space and Earth Science (ROSES), 2024, \$711K  
Co-Is: University of Michigan, University of California Berkeley, Caltech
- Doctoral Consortium at ICCV 2019
- Outstanding Graduate Teaching Assistant Award by the Department of Computer Science, George Mason University, for the academic year 2015-16

## Papers

- *Structure-Preserving Unpaired Image Translation to Photometrically Calibrate JunoCam with Hubble Data*  
A. Singh, S. Shah, R. Sankar, E. Dahl, G. Eichstädt, **G. Georgakis**, B. Bucher  
arXiv:2511.22668 (under submission)
- *A Map-based Localization System for Ingenuity using Deep Image Matching*  
**G. Georgakis**, D. Pisanti, N. Williams, C. Mauceri, G. Kubiak, A. Ansar, R. Brockers  
IEEE Transactions on Field Robotics (T-FR) Special Issue on Space Robotics, 2025
- *Visual Perception Engine: Fast and Flexible Multi-Head Inference for Robotic Vision Tasks*  
J. Lucki, J. Beckett, **G. Georgakis**, R. Royce, S. Khattak  
arXiv:2508.11584 (under submission)
- *Robust Visual Localization in Compute-Constrained Environments by Salient Edge Rendering and Weighted Hamming Similarity*  
T.H. Pham, P. Bailey, D. Posada, **G. Georgakis**, J. Enriquez, S. Suresh, M. Dolci, P. Twu  
IEEE Robotics and Automation Letters (RA-L) 2025
- *Risk-Guided Diffusion: Toward Deploying Robot Foundation Models In Space, Where Failure Is Not An Option*  
R. Thakker, A. Patnaik, V. Kurtz, J. Frey, J. Beckett, S. Moon, R. Royce, M. Kaufmann, **G. Georgakis**, P. Roth, J. Burdick, M. Hutter, S. Khattak  
RSS 2025 Workshop on Reliable Robotics: Safety and Security in the Face of Generative AI
- *General-Purpose Robotic Navigation via LVLMM-Orchestrated Perception, Reasoning, and Acting*  
B. Lange, A. Yildiz, M. Arief, S. Khattak, M. Kochenderfer, **G. Georgakis**  
arXiv:2506.17462 (under submission)
- *Vision-based Geo-Localization of Future Mars Rotorcraft in Challenging Illumination Conditions*  
D. Pisanti, R. Hewitt, R. Brockers, **G. Georgakis**  
arXiv:2502.09795 (under submission)
- *Enhancing the Quality of 3D Lunar Maps Using JAXA’s Kaguya Imagery*  
Y. Iwashita, H. Moe, Y. Cheng, A. Ansar, **G. Georgakis**, A. Stoica, K. Nakashima, R. Kurazume, J. Torresen  
IEEE International Conference on Systems, Man, and Cybernetics (SMC) 2025
- *Illumination Invariant Image Matching for Lunar TRN*  
N. Rothenberger, **G. Georgakis**, Y. Chen, A. Ansar  
AIAA SciTech 2025
- *NAVCON: A Cognitively Inspired and Linguistically Grounded Corpus for Vision and Language Navigation*  
K. Wanchoo, X. Zuo, H. Gonzalez, S. Dan, **G. Georgakis**, D. Roth, K. Daniilidis, E. Miltsakaki  
arXiv:2412.13026

- *Learning Illumination Invariant Features for Lunar South Pole with Deep Learning*  
**G. Georgakis**, A. Ansar  
Space Imaging Workshop (SIW) 2024
- *Pixel to Elevation: Learning to Predict Elevation Maps at Long Range using Images for Autonomous Offroad Navigation*  
C. Chung, **G. Georgakis**, P. Spieler, C. Padgett, A. Agha, S. Khattak  
IEEE Robotics and Automation Letters (RA-L) 2024
- *Icy Moon Surface Simulation and Stereo Depth Estimation for Sampling Autonomy*  
R. Bhaskara, **G. Georgakis**, J. Nash, M. Cameron, J. Bowkett, A. Ansar, M. Majji, P. Backes  
IEEE Aerospace Conference (AeroConf) 2024
- *Unordered Navigation to Multiple Semantic Targets in Novel Environments*  
B. Bucher, K. Ashton, B. Wu, K. Schmeckpeper, S. Goel, N. Matni, **G. Georgakis**, K. Daniilidis  
Embodied AI Workshop at CVPR 2023
- *Bridge Data: Boosting Generalization of Robotic Skills with Cross-Domain Datasets*  
F. Ebert\*, Y. Yang\*, K. Schmeckpeper, B. Bucher, **G. Georgakis**,  
K. Daniilidis, C. Finn, S. Levine  
Robotics: Science and Systems (RSS) 2022
- *Cross-modal Map Learning for Vision and Language Navigation*  
**G. Georgakis**, K. Schmeckpeper, K. Wanchoo, S. Dan, E. Mitsakaki, D. Roth, K. Daniilidis  
IEEE Conference on Computer Vision and Pattern Recognition (CVPR) 2022
- *Learning to Map for Active Semantic Goal Navigation*  
**G. Georgakis\***, B. Bucher\*, K. Schmeckpeper, S. Singh, K. Daniilidis  
International Conference on Learning Representations (ICLR) 2022
- *Uncertainty-driven Planner for Exploration and Navigation*  
**G. Georgakis**, B. Bucher, A. Arapin, K. Schmeckpeper, N. Matni, K. Daniilidis  
International Conference on Robotics and Automation (ICRA) 2022
- *Object-centric Video Prediction without Annotation*  
K. Schmeckpeper\*, **G. Georgakis\***, K. Daniilidis  
International Conference on Robotics and Automation (ICRA) 2021
- *Hierarchical Kinematic Human Mesh Recovery*  
**G. Georgakis\***, R. Li\*, S. Karanam, T. Chen, J. Kosecka, Z. Wu  
European Conference on Computer Vision (ECCV) 2020
- *Robust Multi-modal 3D Patient Body Modeling*  
F. Yang, R. Li, **G. Georgakis**, S. Karanam, T. Chen, H. Ling, Z. Wu  
Medical Image Computing and Computer Assisted Interventions (MICCAI) 2020
- *Towards Robust RGB-D Human Mesh Recovery*  
R. Li, C. Cai, **G. Georgakis**, S. Karanam, T. Chen, Z. Wu  
arXiv:1911.07383
- *Simultaneous Mapping and Target Driven Navigation*  
**G. Georgakis**, Y. Li, J. Kosecka  
arXiv:1911.07980
- *Learning Local RGB-to-CAD Correspondences for Object Pose Estimation*  
**G. Georgakis**, S. Karanam, Z. Wu, J. Kosecka  
IEEE International Conference on Computer Vision (ICCV) 2019
- *End-to-end Learning for Keypoint Detection and Descriptor for Pose Invariant 3D Matching*  
**G. Georgakis**, S. Karanam, Z. Wu, J. Ernst, J. Kosecka  
IEEE Conference on Computer Vision and Pattern Recognition (CVPR) 2018
- *Label Propagation in RGB-D Video*  
Md. A. Reza, H. Zheng, **G. Georgakis**, J. Kosecka  
IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS) 2017

- *Synthesizing Training Data for Object Detection in Indoor Scenes*  
**G. Georgakis**, A. Mousavian, A. C. Berg, J. Kosecka  
Robotics: Science and Systems (RSS) 2017
- *A Contact Exploitative Approach to the Amazon Robotics Challenge*  
E. Dessalene, **G. Georgakis**, Md. A. Reza, Y. Li, Y. Ovcharik, A. Shapiro, J. Kosecka, D. Lofaro  
Warehouse Picking Automation Workshop (ICRA) 2017
- *Multiview RGB-D Dataset for Object Instance Detection*  
**G. Georgakis**, Md. A. Reza, A. Mousavian, P. H. Le, J. Kosecka  
International Conference on 3D Vision (3DV), 2016
- *RGB-D Multiview Object Detection with Object Proposals and Shape Context*  
**G. Georgakis**, Md. A. Reza, J. Kosecka  
IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS) 2016

\* Denotes equal contribution

## Patents Awarded/Pending

- *Method and System for On-board Localization*  
R. Brockers, F. Dietsche, J. Delaune, P. Proença, R. Hewitt, **G. Georgakis**  
US18/312,444 filed May 2023, Application no. US20230360547A1
- *Systems and Methods for Human Pose and Mesh Recovery*  
Z. Wu, S. Karanam, C. Cai, **G. Georgakis**  
US16/995,446, filed August 2020, Application no. US20210158028A1
- *Systems and Methods for Human Mesh Recovery*  
S. Karanam, Z. Wu, **G. Georgakis**  
US16/863,382, filed April 2020, Application no. US20210158107A1
- *Learning Keypoints and Matching RGB Images to CAD Models*  
**G. Georgakis**, S. Karanam, Z. Wu, J. Ernst  
PCT/US2019/053827, filed September 2019, Application no. WO2020086217
- *Matching RGB Images to CAD Models*  
**G. Georgakis**, S. Karanam, Z. Wu, J. Ernst  
PCT/US2019/040913, filed July 2019, Application no. WO2020014170A1
- *Spare Part Identification Using a Locally Learned 3D Landmark Database*  
**G. Georgakis**, S. Karanam, Z. Wu, J. Ernst  
PCT/US2018/049100, filed September 2018, Application no. WO2019094094A1
- *Learning View-invariant Local Patch Representations for Pose Estimation*  
**G. Georgakis**, S. Karanam, V. Manjunatha, K-C. Peng, Z. Wu, J. Ernst  
PCT/US2018/013271, filed January 2018, Application no. WO2019139587A1
- *Training a Convolutional Neural Network using Task-irrelevant Data*  
V. Manjunatha, **G. Georgakis**, K-C. Peng, Z. Wu, J. Ernst  
PCT/US2017/067766, filed December 2017, Application no. WO2019125453A1

## Selected Talks

- **Approximate Photometric Calibrations of JunoCam with a Deep Learning System**  
Invited talk at Juno Science Team Meeting, September 2025
- **Learning Illumination Invariant Features for Lunar South Pole with Deep Learning**  
Space Imaging Workshop, Atlanta GA, October 2024
- **Vision-based Navigation in Novel Environments**  
Jet Propulsion Lab Section 347 Talks, Virtual, July 2022
- **Cross-modal Map Learning for Vision and Language Navigation**  
GRASP SFI Seminar Series, Philadelphia PA, April 2022

- *Uncertainty-based Mapping and Navigation*  
MURI Review Meeting, Virtual, October 2021
- *Object-centric Video Prediction without Annotation*  
Honda Curious Minded Machines Seminar Series, Virtual, January 2021
- *3D Model-Assisted Learning for Object Detection and Pose Estimation*  
GRASP Seminar Series, Philadelphia PA, December 2019
- *Keypoint Learning for Pose Estimation*  
Siemens CT Intern Talk Series, Princeton NJ, August 2018
- *Synthesizing Training Data for Object Detection in Indoor Scenes*  
RSS Conference Talk, Cambridge MA, July 2017
- *RGB-D Multiview Object Detection with Object Proposals and Shape Context*  
IROS Conference Talk, Daejeon, South Korea, October 2016

## Teaching

### *Instructor at University of Pennsylvania*

ESE650: Learning in Robotics with Oleh Rybkin Spring 2022

### *Guest Lecturer at George Mason University*

CS112: Introduction to Programming - Python Fall 2015  
 CS685: Autonomous Robotics Fall 2018  
 CS687: Advanced Artificial Intelligence Spring 2019  
 CS747: Deep Learning Spring 2020

### *Graduate Teaching Assistant at George Mason University*

CS112: Introduction to Programming - Python (Head TA) Fall 2014 - Spring 2017  
 CS310: Data Structures - Java Fall 2018  
 CS480: Introduction to Artificial Intelligence Spring 2019

## Mentoring

### *PhD Thesis Committee*

- Tiberiu-Ioan Szatmari, “*Personalizing Audiology With User-centered, Private AI*”, Technical University of Denmark, 2025

### *Thesis Supervision*

- PhD, Dario Pisanti, “*Vision-based Geo-Localization of Future Mars Rotocraft in Challenging Illumination Conditions using Deep Learning*”, Scuola Superiore Meridionale / Jet Propulsion Lab, 2025
- MSc, Aditya Singh, “*Instruction-guided Path Generation on Allocentric Maps using Diffusion Models*”, University of Pennsylvania, 2023
- MSc, Bo Wu, “*The Role of Mapping in Modern Robot Navigation Tasks*”, University of Pennsylvania, 2023, (jointly advised with Bernadette Bucher)
- MSc, Shiyani Patel, “*Vector Graph Neural Network: Point Cloud Prediction into the Future*”, University of Pennsylvania, 2021, (jointly advised with Karl Schmeckpeper and Diego Patino)
- MSc, Siddharth Goel, “*Navigation to Multiple Semantic Targets in Novel Environments*”, University of Pennsylvania, 2021, (jointly advised with Bernadette Bucher)

### ***Recent Project Supervision***

Isaac Madhavaram (JPL Msc Intern, Summer 2025)

Agata Weglerska (JPL Msc Intern, Summer 2025)

Sofia Talleri (JPL Msc Intern, Summer 2025)

Dimitrios Chatziparaschis (JPL PhD Intern, Fall 2024)

Dario Pisanti (JPL PhD Intern, Spring 2023-Fall 2024)

Jakub Lucki (JPL Msc Intern, Fall 2024)

Haakon Moe (JPL Msc Intern, Fall 2024)

Ramchander Bhaskara (JPL PhD Intern, Summer 2023)

## **Reviewer**

***Conferences:*** NeurIPS, ICLR, CVPR, CVPRW, ICCV, ECCV, WACV, ACCV, ICRA, IROS

***Journals:*** TPAMI, RA-L, Autonomous Robots, Transactions on Robotics,  
Transactions on Image Processing, Pattern Recognition Letters,  
Signal Processing: Image Communication, IEEE Access

***Proposals:*** NSTGRO, SBIR